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Infrared Laser Obstacle Sensor Module

For 110°, 6~200mm Distance

Key Properties

View Angle: 110° ±10° X Resolution: 640 pixels (~0.2°) Sensing Distance: 6mm~200mm(more) Distance Resolution: ±5% *Distance Laser Wavelength: 808nm Eye Safety: Class 1M



Application

Clean Robot / Robot Sensor / 2D X-Y Detection Laser Line Scanning/ 2D(X-Z) Laser Obstacle Sensor

Feature

- FOV 110° wide view angle and infrared sensing with efficiency frame resolution.
 - VGA: X-640 pixels, Y-480 pixels, Frame rate: 30fps
 - The data transfer 27 points data of each frame by 30 frames rate per second.
- Cost effective and quick response solution for image obstacle detection or X-Z scanning sensor.
 - Image processing by MCU and UART transfer interface, resolution and data size adjustable depends on the backend processor ability.
- M12 x 0.5P is convenient for standard S-Mount M12 holder.
- Infrared laser light for eye safety class 1M and environment noise process.
 - The special DOE(Diffractive Optical Element) design for reflecting power intensity uniformity of laser projecting line. It helps the better sensitivity of wide angle and dynamic range of image.

Introduction

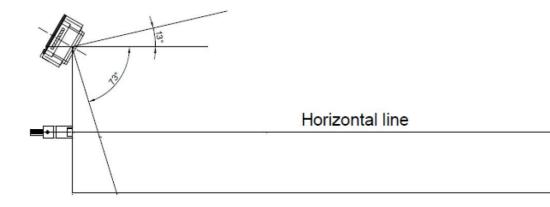
LOS1V110F30 laser obstacle sensor integrates the laser line generator using our own designed DOE for linear uniformity of laser intensity and triangular image processing to simplify and increase the recognition for obstacle sensing in X-Z plane. It can recognize the position including the distance, and form shape of obstacle in front. The wide view angle is designed to 110 degree FOV can be detected and transfer the data rate as 30 frames per second. It can be used for robot, vehicle, auto machine real time detection. As the laser line scan to form a plane shape in front. It also can help the basic mapping in front and distance judgement. This cost effective and convenient laser sensor would be a good solution for image detection.



Specifications

2. OPTICAL CHARACTERISTIC

2.1 Schematic diagram



2.2 Optical Parameter

Items	Parameters			
	Min	Тур	Max	Unit
Sensing distance	60	180	200	mm
			over	
Accuracy at 50~200mm(Y value)	-5%	-	+5%	mm
Optical output power.		20		mw
Wavelength	803	808	813	nm
Line Span Angle	100	110	120	degrees

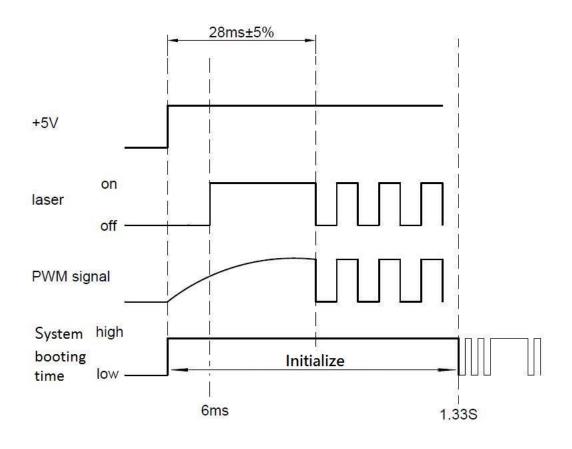


3. ELECTRICAL CHARACTERISTIC

3.1 Schematic diagram



3.2 Time diagram





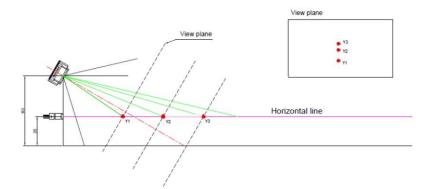
3.3 Electrical Parameter

Items	Parameters				
	Min	Тур	Мах	Unit	
Operating Voltage	4.8	5.0	5.3	V	
Operating Current	124	140	160	mA	
Baud Rate	2%	115200	2%	bps	
PWM Frequency	-	3.3K	-	Hz	

4. ALGORITHM

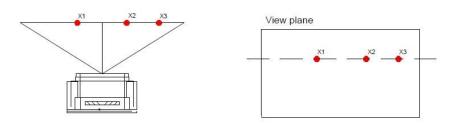
4.1 Diagram

Y direction: 480 pixels



Note. Sensing target need add the necessary distance for the radius of turn of the robot or vehicle to avoid the obstacle making the corrections in firmware.

X direction: 640 pixels



Data format:

in binary, short integer frame separator begin and end: $0xCC \ 0xCC$

horizontal line and down line separator: 0xDD 0xDD





- 4.2 Horizontal Line Data
 - X,Y data bytes length:2
 - X,Y data type: short integer
 - X,Y data fixed: 27 points

For instance:

0XCC	OXCC	0X00	0X64	0X01	0XF4	0X00	0X32	0X01	0XF4
Begin fr	rame	X-high	X-low	Y-high	Y-low	X-high	X-low	Y-high	Y-low
separat	or	byte	byte	byte	byte	byte	byte	byte	byte

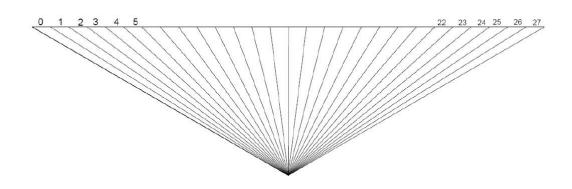
PS: 0x00 0x64 = 100; 0x01 0xF4=500;0x00 0x32=50; (unit:mm)

Means (100,500), (50,500) have object reflect the Horizontal line.

X value in [-600 to 600]

Y value in [0 to 1000]

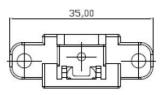
0x	0x	0x	0x	0x00	0x32	0x01	0xF4
X-high	X-low	Y-high	Y-low	X-high	X-low	Y-high	Y-low
byte	byte	byte	byte	byte	byte	byte	byte

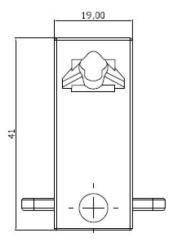




5. DIMENSION & MODULES & CONSTRUCTION

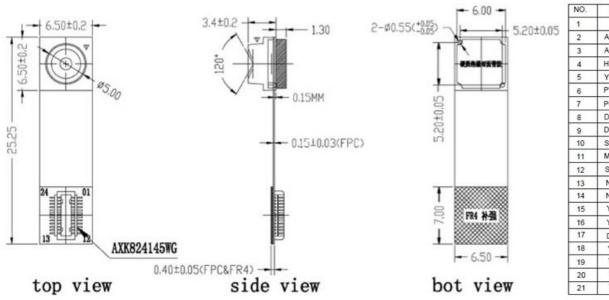
5.1 Casing







5.2 Camera Module



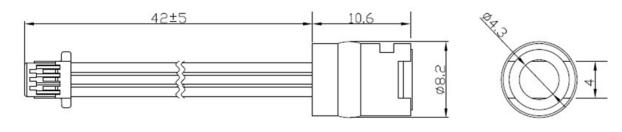
CONNECTOR 24Pin DESCRIPTION

NO.	SYMBOL		
1	NC	22	RESETE
2	AVDD_2V8	23	¥6
3	AGND	24	¥7
4	HREF		
5	YSYNC		
6	PWDN		
7	PCLK		
8	DVDD_1V8		
9	DVDD_2V8		
10	SI0_D		
11	MCLK		
12	SI0_C		
13	NC		
14	NC		
15	YO		
16	Y1		
17	DGND		
18	Y2		
19	Y3		
20	Y4		
21	Y5		

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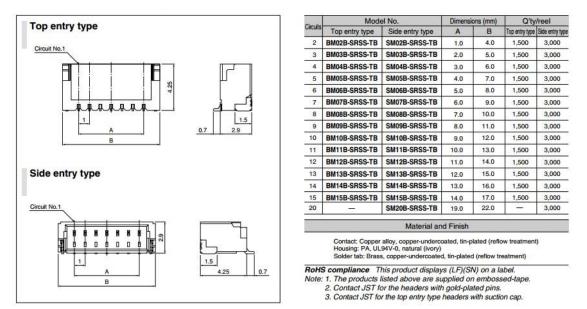


5.3 IR Laser Module



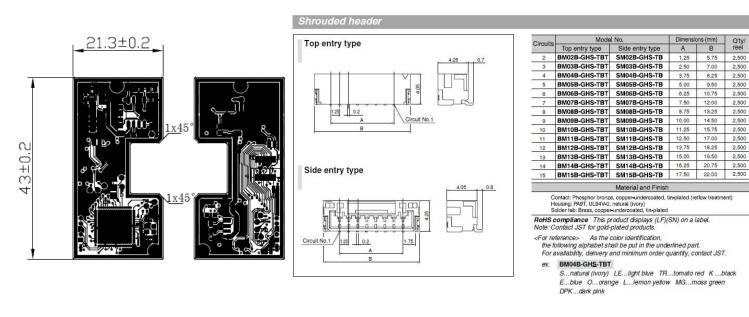
UL 1571 AWG 28# WHITE/BLACK/RED WIRE

Laser Module Connector: BM03B-SRSS-TB



5.4 PCBA Dimension

PCBA UART Control Connector: BM05B-GHS-TBT





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6. RELIABILITY

Item	Method	Criteria
Thermal Cycle Test	Temperature cycle: -20°C(2Hrs), 60°C (2Hrs) Cycle time:7 cycles Transfer time:1hr	No losing and function fail
Cooling Test	Temperature: -20 ±1°C Time:168hrs	No losing and function fail
Heat Test	Temperature: 60 ±2°C Humidity: under 35% Time:168hrs	No losing and function fail
High Temperature & Humid	Temperature: 40 ±1°C Humidity: above 90% Time:168hrs	No losing and function fail
Thermal Shock(PCB)	Temperature cycle: -20 °C (30min), 80 °C (30min) Cycle time:750cycles Transfer time: under 10 seconds	No damage, crash
Vibration Test(PCB)	Frequency : $5 \sim 55 \sim 5$ Hz range : 1.5mm Time : 1min Method : logarithmic frequency sweep Direction & Time : X,Y,Z (each 2hrs)	No damage, crash
ТНВ(РСВ)	Temperature:85 °C Humidity: above 85% Cycle: 1hr on, 3hrs off Time:500hrs	No damage, crash

7. OPERATING & STORAGE TEMPERATURE

Operating Temperature	-10~45 °C
Storage Temperature	-20~60 °C

8. CERTIFICATION

8.1 CLASS 1M (IEC60825)

8.2 ROHS

Laser Safety

The light emitted from these devices has been set in accordance with IEC60825. However, staring into the beam, whether directly or indirectly, must be avoided.

Class I

The maximum permissible exposure(MPE) cannot be exceeded, it includes High-power lasers within an enclosure that prevents exposure to the radiation and that cannot be opened without shutting down the laser. For example, a continuous laser at 600nm can emit up to 0.39mW, but for shorter wavelengths, the maximum emission is lower.

Class II

"Caution", visible laser light less than 1.0mW. Considered eye safe, normal exposure to this type of beam will not cause permanent damage to the retina.

Class IIIA

"Danger", visible laser light between 1.0mW and 5.0mW. Considered eye safe with caution. Focusing of this light into the eye could cause some damage.

Class IIIB

"Danger", infrared(IR), and high power visible lasers considered dangerous to the retina if exposed. NB: it is important to note that while complying with the above classifications, unless otherwise stated. Our laser diode products are not certified and are designed solely for use in OEM products. The way in which device is used in the final product may alter its original design classification, and it is the responsibility of the OEM to ensure compliance with the relevant standards.

Specifications are subject to change without notice.



